



Contextual System-Theory

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Abstract

Introducing a new contextual system-theory, with focus on analysis of biological systems, give a guideline of how to explore complex systems. It is written not only for scientists, therefore I try to describe part of the way understanding complexity as an intuitive approach. This will also help scientists to get a deeper and more complete understanding of complex systems. Some definitions and rules may seem at first simple and obvious, but practiced in a multidimensional complex surrounding, one will see the difficulties. Even without mathematization or computer modeling a multidimensional sub space, which we try to describe phenomenologically for approaching the understanding, will need a lot of training not getting lost in the multidimensional world. Some of the chapters here and in following publications of this series are written for specialists, but we always come back to the essence of a phenomenological description. Concepts like Symbolic programming, Object oriented modeling, simulation, optimizing as well as experimental mathematical approaches and using new ways of artificial intelligence are the described tools to “unpuzzle” complex scenarios. The whole world interferes in many dimensions with the little world around us. If we do not want to destroy it with our one-dimensional solutions, we need to look at its problems in a new way.

The present living in today’s global world is more complex than ever and complexity will increase dramatically in the future. We ourselves still tend to think linearly looking for simple answers. Our brain likes to live in the Stone Age where our horizon had a radius of several kilometers, but the influences to our lives and the related interconnections do not end in the next village or the next kingdom. The whole world interferes in many dimensions

with the little world around us. If we do not want to destroy our world with our simple views and one-dimensional solutions, we need to learn to look at it and its problems in a new way. The comparison between the described approach of the contextual system theory and others are part of one of the last publications of this series of articles. Aside of their solutions, which will be taken into account as examples to describe complex systems, other approaches will then be discussed.

Keywords: System-analysis; Complex systems; System-theory; Biological systems; Object oriented programming; Artificial intelligence.

Introduction

For more than hundred years we have lived in an age of science. Natural science and technology have determined our thinking and daily activities. Looking for causal dependencies is the basis of our arguments in any discussion. What we are not aware of is, that all causality we argue with is

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Citation: E.K. Wolff. Contextual System-Theory. Journal of Analytical Techniques and Research. 7 (2025): 23-29.

Received: April 07, 2025

Accepted: April 14, 2025

Published: May 20, 2025

based on models. Even though these models are very often derived by a good reliable database, none of these models can be really verified. They may have a high plausibility and thought to be "true", but if one looks closer into it, the "reality" is much more complex. G. Nicolas and I. Prigogine wrote at the beginning of their book [1] "Exploring Complexity": "Our physical world... is a world of instabilities and fluctuations, which are ultimately responsible for the amazing variety and richness of the forms and structures we see in nature around us. New concepts are clearly necessary to describe nature, in which evolution and pluralism become the key words."

For almost the same hundred years, scientists debate about causality. In the beginning of the nineteenth century paradigm changes were introduced. It all started with nuclear disintegration and quantum-mechanics. Only introducing statistical behavior into the new types of models fulfilled the non-causal descriptions of the observed phenomena. In addition, Heisenberg showed with his uncertainty principle [2] that even two dimensions of a System cannot both be exact, so distribution-functions were introduced. All the models we use are simplified for our limited human view. We never learned complex thinking in school or even in university. Part of this is due to our evolution. In extreme situations (for our early ancestors: Human - Lion Situation) we have to be able to make fast decisions. So our brain developed to simplify and minimize, to decide fast and linear. In an evolutionary sense, we are in a Stone Age state and cannot keep up with the technical and scientific revolutions of the science century, but our own environment has changed to be much higher in complexity. Globalization and environmental problems form world networks of interdependencies, which cannot be described with simple system models. Even in modern science one starts with a simple model to explain an isolated case of a complex system. Then gradually the model is built up step by step to a more complex situation. This approach I call inside-out modeling. It works fine in low complexity and ideal model situation, but to describe high complex systems, one needs a paradigm change turning the procedure upside down. In the following chapters the basis of a "Contextual System-Theory" for modeling complexity as an outside-in procedure will be developed.

Methods and Definition

The *whole* is the whole, it includes everything. All that exists; all that was thought or can be thought of; all laws and their contraries; meaningful or meaningless and much more; all that one can imagine or never be able to. Just,

All

If one turns the classical procedure upside down, one has to start with the whole, the whole world or everything. This will be called the

All-System or shortly **A**
The
exists of all **All-System A**
elements e
which are **existent**
An **element e** is **existent**, if it is
experienceable (experimenting) ε
by itself
Self-experienceable iε
intrinsic-existent or self-existent
or by another **element e**
extrinsic-experienceable eε
extrinsic-existent
Describeable d (describing) means, the **experienceable element e** becomes a
structure s
Communication c

is the transfer of a **structure s** to an (other) **element e**

Let me pause for a moment before continuing with the definition part and discuss some consequences. Thinking for example is a sub form of **describing d** so it forms in self- **communication c** with the **element eb (brain)** a new **structure sb** in itself, if one locate thinking to the brain.

Another consequence is, **c** effects our communication language. **Languages Sl** are **Systems**, which have a **structure sl**, determined essentially by its **grammar el** and its **syntax ol**.

Time, Sets, Context and Operation

The **All-System A** include the **element et**, short **t** the **Time** (even if one include the relativity theory of Einstein, one would need to take the space-time into account). Only a system including the **Time t**, can be closed. It is self-evident, that the **All-System A** is closed.

Parts of the **All-System A** can be divided into

which consist of the **Subsystems S**
elements es

represented symbolic in the descriptive graph of figure 1.

To each of the above and further described - defined instances - exist an associated set **M**. For example **MA** or **MS** are the associated sets of the **All-System A** and **Subsystems S** respectively as displayed in figure 2.

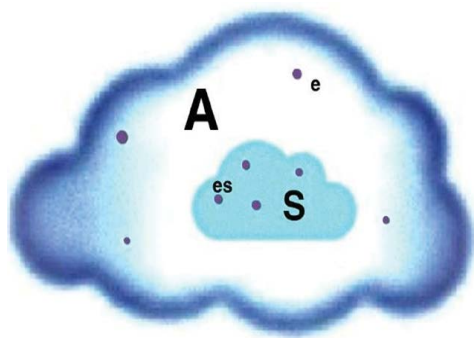


Figure 1: Descriptive graphic representation of the All-System A and the subsystem S with their elements e and es

This step reflects two representations of systems. The first one is the descriptive and more general holistic one, which is open, "formless" and does not have to have rules, although it can. The second one is the formal one with defined rules and structures.

While introducing the formalism of sets, one already mathematize and starts to model using mathematical rules and a mathematical language. As it will be shown later, sometimes one even has to find new formalisms to expand the classical mathematical language, fulfilling necessities for describing phenomenons, which cannot be handled with classical mathematics.

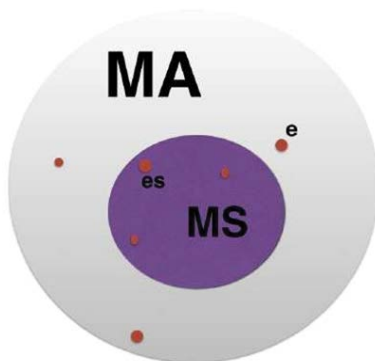


Figure 2: Formal graphic picture of the sets MA and MS with their elements e and es

All **Subsystems S** as well as all **elements e** are connected by **interactions actions α**

It follows directly, that **actions α** are part of the **experienceable (experimenting) ϵ** (consequently communication c is an action). For more clarity we will call all **experienceable actions** with the elements **e** as **ϵ** giving **e** a structure **s** while **α** describe more the **interaction** between two or more **elements** (figure 3). It can also form structures in elements. (For example: a ball reflects in the interaction with a white light source red light and is noticed by our eyes as a red ball. But if the light source is pure green, the ball is black for our eyes. Is it now black or green?).

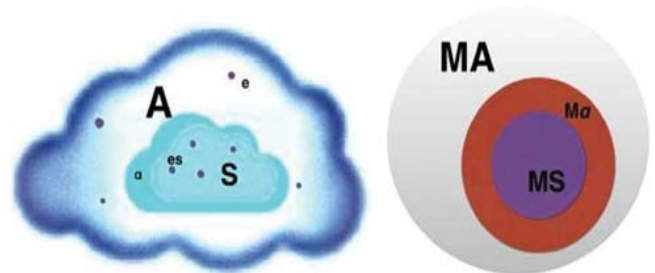


Figure 3: Descriptive (left) and formal (right) representation of the interactions to the allsystem

Everything has a context. Complex systems especially have to be viewed in connection to their contexts. One tend to simplify this aspect and forget the complexity of the interactions to other systems and its surroundings. The most mistakes one easily makes, is to presume the reproducibility of the contextual situation. One always has to obey the time dependence of the context in modeling complexity. Developing a new system theory it is necessary to include the context. The

Context KS

Is a Subsystem which includes the **Subsystems S** and all **actions as** from **Subsystems S** with the rest of the **All-System A**. So all

actions as are **KS-S**.

The same should be true for all associated sets **M**.

As important as obeying the contexts of systems, is to look differently to our understanding of time dependency. All system-**elements e** are time dependent as well as their **actions at**.

What is usually called constant is never time independent. One could formulate it possibly the way, that **at** is a process, with no measurable change in times of single "infinity". (What ever "infinity" means, it has to be defined for every case).

$$at(0) \sim at(t) \text{ and } at(t) \sim at(t+\infty)$$

A **Subsystem S** can be self-identical, but two **Subsystems S1** and **S2** can practically never be equal, because of the high context sensitivity **KS**, statistical **elements es** **part of the set of es** and its time dependence **est**. Therefore, let's introduce:

proximity ϵp

Similar **Subsystems S** form in the n-dimensional System-space cluster which have a **proximity ϵp** , where all **Subsystems S** have the **Distances ed** from each other.

The **Distances ed** themselves are elements of the associated **Subsystems S** or structures of its elements. So the **proximity ϵp** describes the distribution of the **Distances ed** in the cluster. Instead of talking about "equality" we should

think about “similarity”. In the place of “comparable” we put “categorization” - that means: to order in **Distances ed**, the relative closeness in the n-dimensional system space. The categories have no fix borders like drawers, they form open like clusters. These differ from other clusters in their different probabilistic centers.

It is a basic principle of complex systems that they can be contextualized. Because of the statistical part of the system parameters and elements, the context will be variable and fluctuate in time.

So the stability of a system is always a function of time, and it depends on the elasticity and therefore on the adjacent contextual laws of the System. All systems are time unstable or better “quasi stable”, only the spaces (system owned period) of time are different, depending on the context. The natural laws, part of our mathematical view to the world, belong to this context.

The characteristic space of time of special systems vary a lot, even in similar system- domains. For example in living systems the space of time-domain starts with ms (e.g. flies etc.) and ends with several thousand years (e.g. trees, funguses etc.). The time-domain of lifeless material reaches from atoseconds or smaller to the existence of the universe (e.g. elementary particle systems, quantum mechanical systems, geological systems, astronomical systems etc.).

One consequence of this part of complexity is the deterministic chaos of systems such as, the butterfly effect, which E.N. Lorenz described [3,4] for the first time, that weather is influenced by the beat of a butterfly’s wing even far away from us. One does not have to look for such high complexity like meteorological systems to find deterministic chaos, already the three - body system is unpredictable in its time course and forms a deterministic chaotic system.

The second consequence of complexity, due to the Heisenberg uncertainty principle, follows as the fuzziness of complex systems. A similar effect will arise from indeterminable fluctuations like statistical noise. So it is essential to include these aspects into the system’s description or modeling. In logic type of modeling, you could use fuzzy-sets, while in the mathematization of complex systems one needs statistic-operators like in quantum mechanics. All these effects will be discussed further in a later publication of this series as well as the symbolic visualization of complex systems like Feynman [5] visualized in his graphs the complexity of quantum interaction in elementary particle physics. This kind of graphical approach could be developed for complex systems as well.

The Operation Ω

is an amount named classes of **actions as** to do experiments for describing **Subsystems S**. This can be a

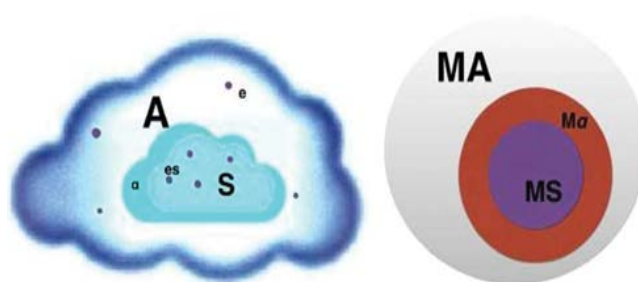


Figure 4: Graphic demonstration of cutting (descriptive (left) and formal (right))

personal subjective **Interpretation is**, or a more objective **Analysis os** by a measuring system like in analytical methods (Spectroscopy, NMR, ESR, AFM, Electro Microscopy etc.). Neither of these are ever complete, because the subject can never sense all possible properties of **S**, nor are all known apparatus or measuring systems able to do it. So the described **Subsystems S** falls into two parts, **Subsystems SK** the known one and **Subsystems SU** the unknown (figure 4).

Another operation, processes of analysis, we have to define, I call **cutting**. This is the process of analyzing the Subsystem and categorizing the Subsystem with its interactions **a** due to the **All-system A**. Or another subsystem **S0**, which includes the subsystem **S** totally or partially. This way we define the borders of the Subsystem due to it’s surrounding in the n-dimensional space.

The **cut C** defines the borders of the subsystems to its surroundings of **S0** or the space of the **All-system** or both. It can be inclusive “**Ci**”, so all objects lay inside of the Subsystem **S** and are Elements of it, or exclusive “**Ce**”, where all Elements are outside and not objects of **S**. A mixture is possible. In this case the **cut Cie** has to be defined for each dimension or classes of dimensions of its n-dimensional system-space separately. Very often one can approximate it by a distribution function.

At this stage the defining part gave all necessary definitions so far and we can start to practice describing real systems.

Results

From here on, part of the “modus operandum” of modeling complex systems will be described. Later articles will go deeper into the whole process of contextual system-analysis and its steps. First I formulate the classical way of going “inside-out”, following turning this around going “outside-in”. Let’s start with a putative simple system, **a ball**.

A Ball

Lets throw a small, heavy ball and describe its three demential way in time. Classically we would use Newton’s laws of universal gravitation and get pretty good results. If

we take a larger ball, which is even lighter, we have to add aerodynamic resistance and in case of upcoming wind the situation becomes quite complicated. But still we just take the basics of

Newton's laws and combine it with other classical physical principles. If the situation is normal, which means average, everyday conditions, we get for the most part (excluding extreme cases) good, practical approximations. Even if the use of other more complex mathematical descriptions would not fulfill our needs. We normally solve all these problems via numerical approximation, irrespective of the concrete conditions, like having water instead of air or other media such as a beach ball instead of a small heavy one and so on. We can simulate almost all usual circumstances precisely enough with modern numerical techniques. What will fall by the wayside using this approach, is the deeper understanding of the underlying dependencies. As a soccer fan, I would like to know how to curl the ball from 20m away directly into the top right corner of the goal. The special outer surface, as well as the spin and inner inhomogeneous fluctuations of the ball, are partially responsible for the movement. As far as I know, no one has yet found a reasonable way to explain this. Only the striker himself, with intensive training, can learn to kick the ball, with good probability, into the top corner.

The process, starting with a simple model and refining it by adding more complexity, will obstruct the view to the whole. Let me therefore at this point change to the outside-in procedure.

We start with the **All-System A** wherein our ball **SBall** is a subsystem, which does not contain only the balls,

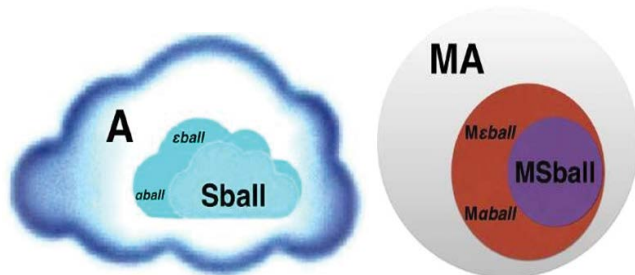


Figure 5: Principal representation (descriptive (left) and formal (right)) before brainstorming

I was talking about, but all the balls one can think of and even the ones we cannot imagine. As kids we used a can or crumpled sheet of paper to play soccer, this was our ball. In rugby or American football the form is more of an egg-like structure than a sphere. All of this, color, material and so on are experiences with the ball and are described by **eball** the **interactions** we summarize in **aball**. The following figure 5 shows this situation in the general descriptive (left) or more

mathematical form (right).

The next step is brainstorming about all what we understand about balls, their properties as well as all interactions between the balls and with their surroundings. This is one of the most

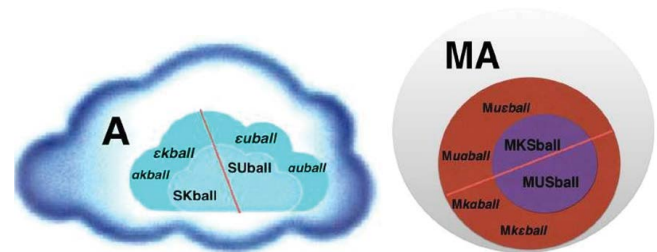


Figure 6: Principal representation (descriptive (left) and formal (right)) including the unknown

important steps in the whole analysis and it has to be done thoroughly without missing any developments in the field of balls and the associated ones. This step has to be fulfilled all the time iteratively to be as complete as possible.

After this we set the cuts, which is just as important and also needs conclusive brainstorming to determine which are not balls. It will give us the borders to the **All-System A** and the associated **Subsystems S**. So we get the following situation, shown in the next schemes (figure 6).

Why do I make a ball so complicated? First of all it is a simple example to demonstrate the principles of the outside-in system-analysis. Secondly, if I include a satellite being part of balls, it becomes even clearer for such a simple example, as a ball. Suddenly, if the satellite flies for several ten years in space to reach the far astronomical objects of our solar system, the space-time, the space-curvature, quantum-relativity etc. has to be included and the ball becomes a much more complex system. So the model of our ball is highly dependent how looking at it.

The surrounding, its objects and their interactions with the subsystem **Sball** I call the **Context Kball**. The **Context K** of a **Subsystem S** summarizes all *experienceable* ϵ and with it all *actions* α between the outer elements of **S**. The graphic representation of inner elements will be discussed in the next article in details.

Let's come back to earth, there is enough complexity here in our daily life.

A Forest

A Forest is a highly complex system, which forms its own biocoenosis. A lot of subsystems are working together. Not only that, this biocoenosis is not understood, this is true for almost all its subsystems and even the trees themselves. As an exception we will in this case start with the cut, because we define, for ease, the subsystem forest, **SForest** as an area

of trees. This means, where the trees end is the border of what we call a forest. But where do they end? This is not so easy to decide. For that the mean distance ϵdm of the trees has to be defined to know when an area is a forest. The distance ϵd is an operator, which describes in the mathematical approximation the density-function in the forest area. If we take the distribution function as the measure for defining the forest we define the border as 5 times the mean of ϵd . Each tree, which lies on its own outside is not part of the forest. (In practice it is much more complicated as described here - were starts the savanna, were ends the forest? - this will be discussed in a later article dealing with forest).

Now let's start with the brainstorming. We count first all subsystems of the forest, assigned as **SSForest** - the trees **STree**, where we include all bushes to get a better cut for the subsystem **STree** (the differences between trees and bushes are taxonomically not always clear) - the other plants which are not trees as **SPlant** - the animals, which live their life in the wood as **SAnim** - single cell organisms **SOrga**, which do not belong to either plants or animals - bacteria **SBact** - viruses and phages **SVir** - last but not least the inorganic part of the soil **SSoil** and the surrounding air and gases **SAir** - for something we might have missed, **SRest**.

We made it simple to define the cut but this does not mean we should not consider the interactions to the **Allsystem A**. Let's form classes to easier keep track of all interactions. The first are the interactions to the two main compartments of the wood. Inside the ground (soil) we call ϵs , as and outside the ground (in the air) ϵa , aa . While there are interactions ϵb , ab , which interact with both parts of the wood, the air and the soil compartment. Light, or in general electromagnetic waves, for example acts upon the plants and heats up the soil. Or human visitors walking through the wood influencing the air part (fleeing animals, etc.) or as well as the soil part (soil compaction, etc.).

On the other hand we have material exchange between the **All-System A** and the wood leaving elements **SI** or entering once **Se**. All of these with its interactions might have a big influence to the biocoenosis. The tree orchids in the Brazilian rainforest for example get their minerals from soil parts of the Sahara brought by intercontinental airflow.

Last but not least, we have the class of interactions ar , which we do not know or did not consider. The inner interactions in the System forest, **SForest** and between its subsystems will be discussed in a separate article, where we describe and model, **SForest** in more detail. The following picture summarizes symbolically the situation (figure 7).

At this point I will leave the examples, to go on with it, would fill chapters, which I will describe at a later stage, if we have learned more about the formalisms and techniques

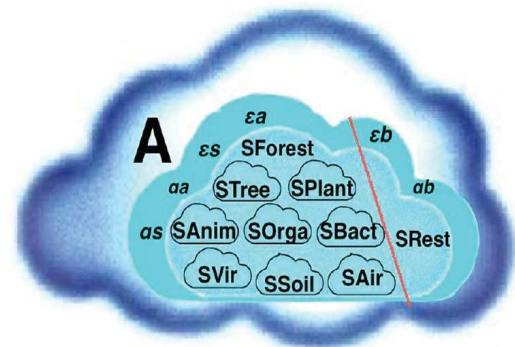


Figure 7: Principal descriptive representation after a first brainstorming

of modeling complex systems in a contextual system theory several real systems will be described in a following series of articles handling complexity.

Conclusion

As one might have noticed, the described definitions above are very close to the definition and strategy of object oriented programming like in Smalltalk or Java. I did this on purpose as it is the way to transfer the descriptive model almost directly into an object oriented program surrounding for modeling the complex system behavior embedded in its context. So a forest with its very high complexity and its even more complex context, can almost intuitively be formed into a computer model representing the thoughts combined with the scientific results and different mathematical descriptions. Using the modern tools of artificial Intelligence enables us to model high complexity by applying the iterative learning as an approach for getting answers in a complex world. In the future a formalism of symbolic representation of complex systems based on the described definitions should be developed helping us to ease understanding complexity. Using all the tools including mathematization, plausibility and the consequences of our intuitive view to complexity can be proven. Inconsistency will easily show up and by expanding the model into the future even small deviation to the reality will teach us where our thinking is wrong or fits the reality. This way leads to new research and experiments, clarifying our view, enabling us more and more to think about complexity and to leave the linear world.

Aside of this more intuitive formulation, it is important to integrate existing scientific laws and models into the description of complex systems. In a later article I will describe how several mathematical formulations, like matrix algorithm, operator formalisms or graphic calculations can be enclosed into the descriptive part. Transformation techniques like Fourier transformation, Recurrence plots, Phase space representations etc. help us to visualize special aspects in complex systems. It is important, that the state

of the art in mathematics and science is always part of our view to complexity. Only obeying all the knowledge about the analyzed systems will bring us closer to the insight into the whole context and one can overcome the restricted view of a single science. This is of especially high relevance if we look at natural systems or human beings. The findings of Biophysics, Biochemistry, Molecular Biology, Evolution, Psychology, Sociology, Medicine and many more sciences have to be brought together, to get a reasonable view of our species. These will be the main topics of the following articles.

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